

New detectors

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- Silicon calorimeters
- Aerogel RICH
- Ultra fast silicon detectors (UFSD) for 4D tracking

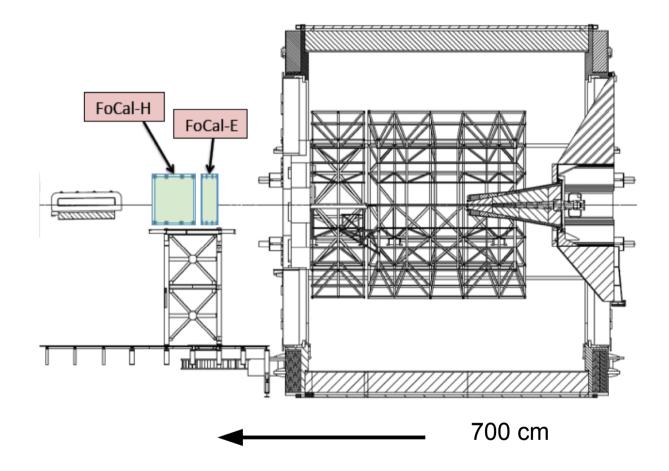
Look for recent conferences on instrumentation: INSTR-17: https://indico.inp.nsk.su/event/8/overview

- Goal: measure with high precision electrons and photons at very high rapidities in collider experiments
 → need for extremely high angular resolution to separate individual showers
- Need compact, highly segmented and fast calorimeters with imaging capabilities
- Not based on proportionality of deposited energy, but on counting the number of showering particles

Silicon detectors (strips or pixels plus pads) coupled to an absorber: Few tens of layers (20-30) + segmentation to few squared millimeters This also shows very good radiation hardness

Example project: FOCAL in ALICE (under study)





Goal: separate close-lying electromagnetic showers and reconstruct their direction with high accuracy

- High lateral segmentation to discriminate between the large number of particles incident on the detector, specifically distinguish direct photons from those coming from π^0 decays
- Absorber material: tungsten: Moliere radius 10 mm

radiation length 3.5 mm

20 layers, about 1 X_0 each

• Sensor material: silicon

Alternate layers with fine segmentation to others with rougher segmentation to limit costs and the volume of data collected

 High granularity: CMOS MAPS (30 µm x 30 µm) Low granularity: pad sensors



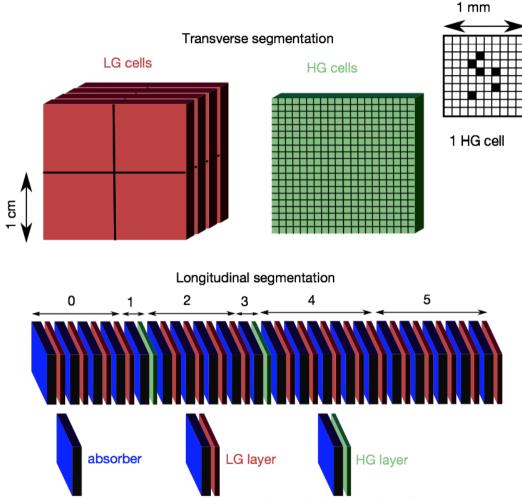
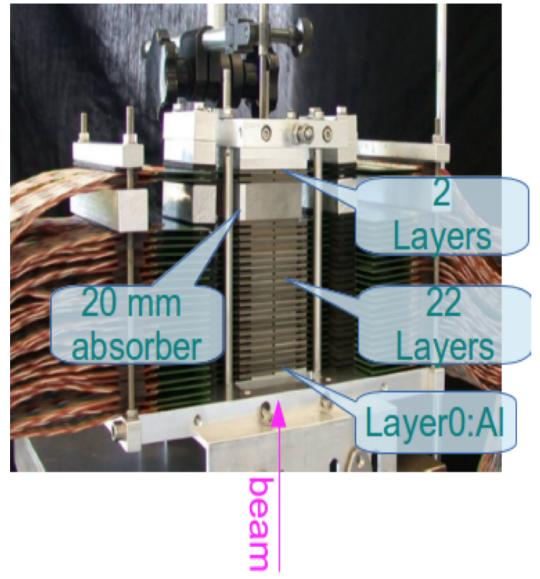


Figure 2.13: The concept for the FoCal detector. (below) Absorbers (blue) will be approximately 1 X_0 of depth, with low granularity (red) and high granularity (green) sensor layers inserted between them. Independent readout units are indicated by numbers, with the low granularity layers being summed 4 to 5 layers deep, and the high granularity layers being read out independently. (above) Illustration of the difference in granularity of the low and high granularity cells.

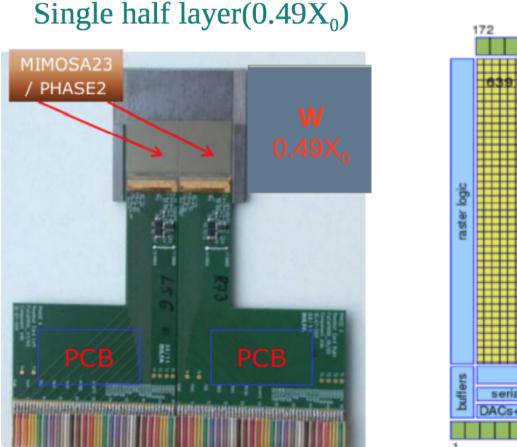
Stack of W and Si layers

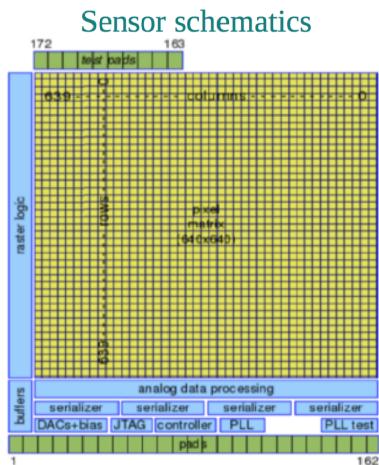




CMOS silicon sensor

- PHASE2 MIMOSA 23 [3]
 - * 640×640 pixels
 - * Pitch: 30µm
 - * Rolling shutter
 - * 640µs/frame





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New detectors, October 13, 2017

Number of hit pixels proportional to energy of incoming particle

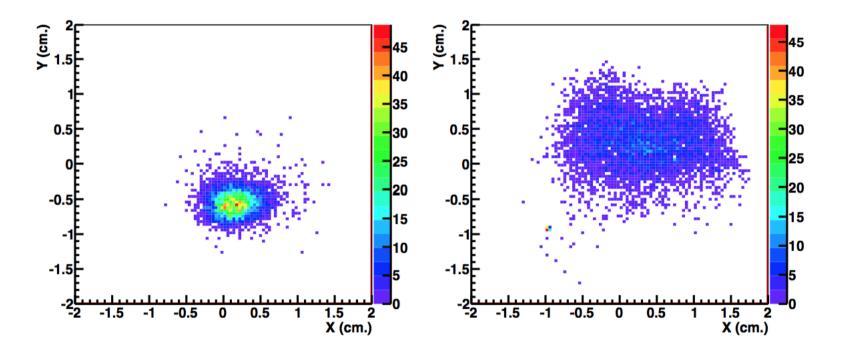


Figure 5.8: The distribution of the location of tracks (left) and the location of showers (right), a splitting of the beam into 2 types of interactions can be seen at data obtained at SPS at 100 GeV/c.

Number of hit pixels proportional to energy of incoming particle

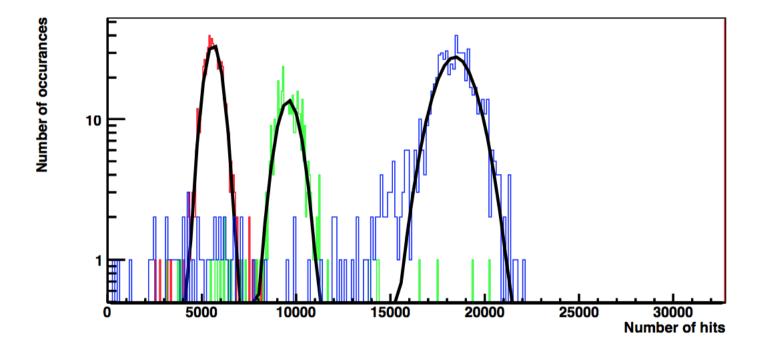
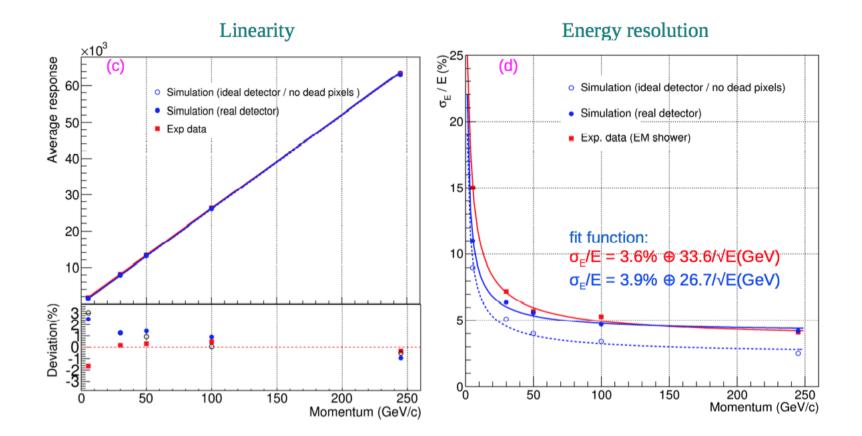


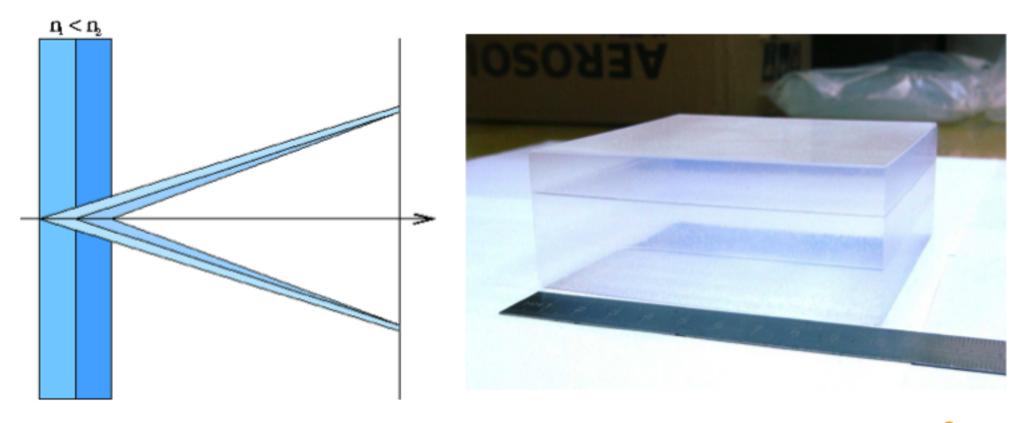
Figure 5.9: Distribution of hit pixels for e^+ at $30 \,\text{GeV}/c$ (red), $50 \,\text{GeV}/c$ (green) and $100 \,\text{GeV}/c$ (blue), as measured at SPS as in figure 5.7. In addition cuts on the shower position based on the results of the analysis of figure 5.8 are applied.

Results: linearity and energy resolution



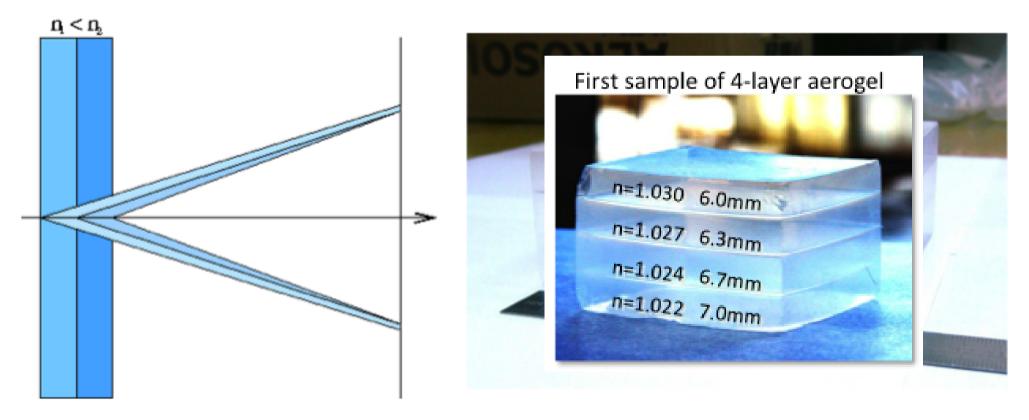
QM2015 poster by Chunhui Zhang

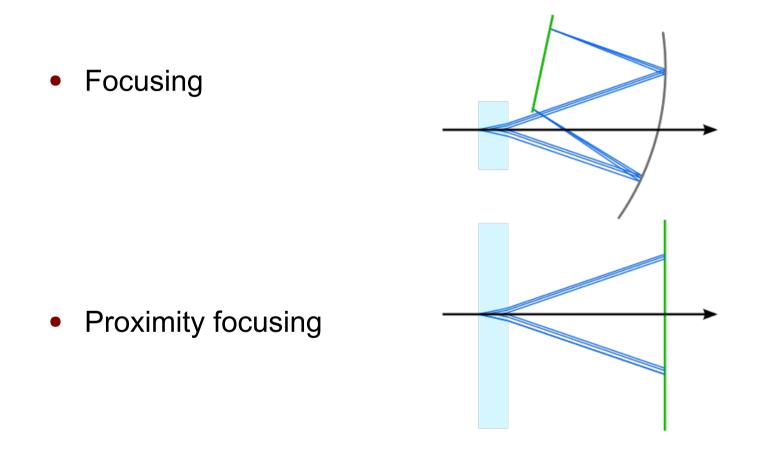
- Use aerogel for radiators (n=1.035 1.06) to allow π/K discrimination at "higher" momenta (4-10 GeV/c)
- Focusing aerogel RICH: improves proximity-focusing design by reducing the contribution of radiator thickness to the Cherenkov angle resolution



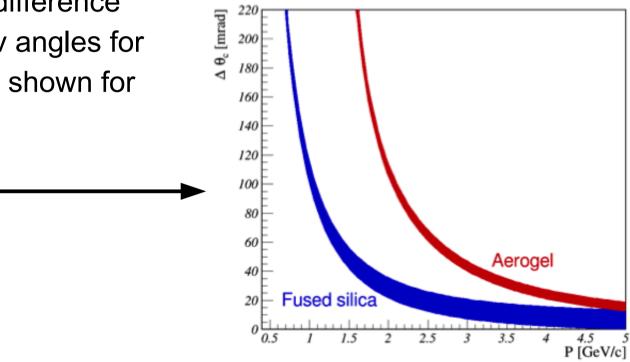


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- Aerogel layers allow compact RICH designs
- Provide a much larger difference between the Cherenkov angles for different particles. Here shown for pions and kaons



 Photon detection with powerful SiPM (single-photon sensitive device based on Avalanche PhotoDiodes, APDs – analog) or DPC (Digital Photon Counter - digital)

Other compact RICH detectors

- Radiator = gas under pressure
- Example: pressurized C4F8 (1 m long) plus GEM stack structure to detector photons

Pressure: 3.5-4 atm

Clear π, K, p separation up to 32 GeV/c obtained with a prototype in a test beam

Ultra fast silicon detectors for 4D tracking

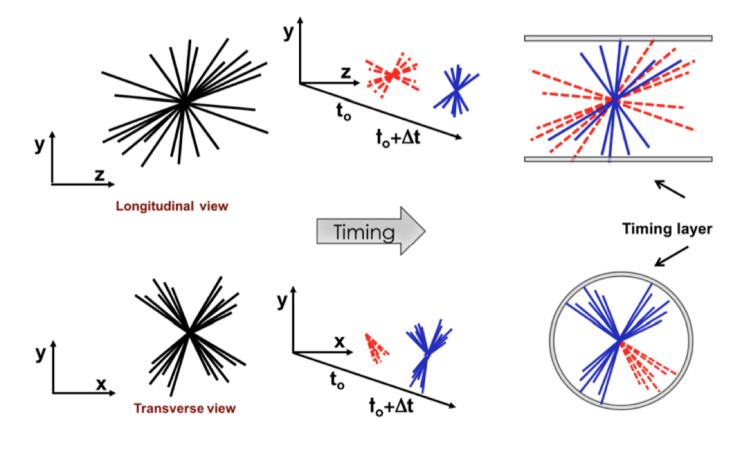
- Development lead by RD50 and several Italian groups (N. Cartiglia, V. Sola et al.)
- 4D tracking: to cope with
 - Extremely high interaction rates and pile-up High-Luminosity LHC: 150-200 collisions per bunch crossing
 - High rate interactions in fixed target mode → no bunch crossing information (CBM, PANDA at FAIR)
- Goal: 4D event reconstruction with a spatial resolution of 20-50 µm and time resolution of 10-20 ps



UFSD

TIMING IN THE EVENT RECONSTRUCTION

➡ Timing allows distinguishing overlapping events by means of an extra dimension

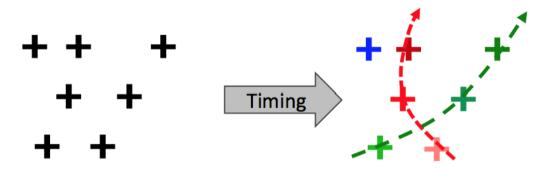




Material from V. Sola IPRD16 Siena

TIMING AT EACH POINT ALONG THE TRACK

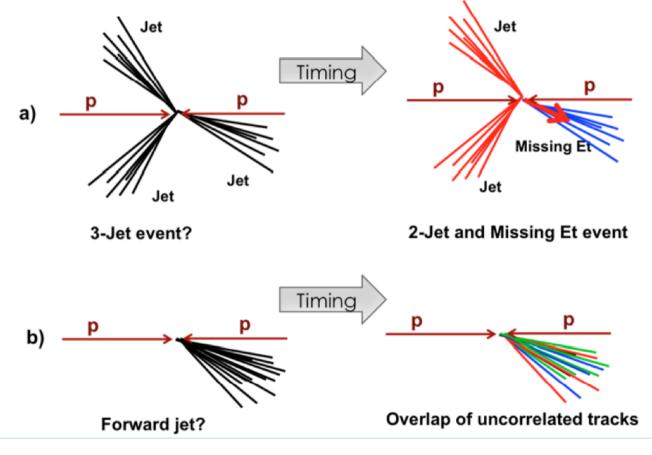
- Massive simplification of pattern recognition, new tracking algorithms will be faster even in very dense environments
- Use only time compatible points



UFSD

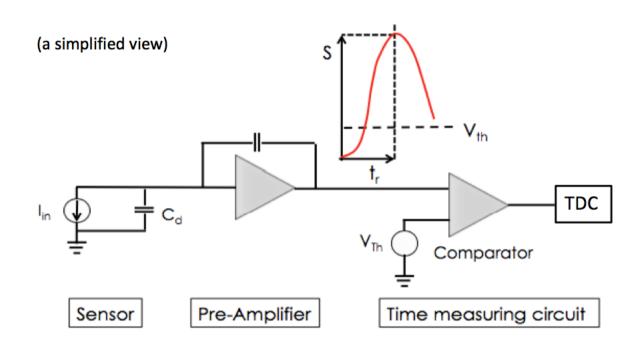
TIMING AT THE TRIGGER LEVEL

Timing at the trigger decision allows reducing the trigger rate rejecting topologies that look similar



UFSD

A TIME-TAGGING DETECTOR



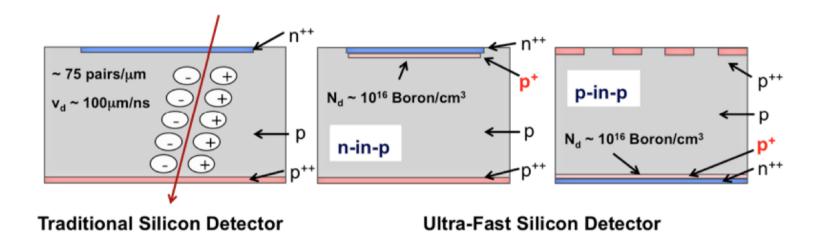
Time is set when the signal crosses the comparator threshold

The timing capabilities are determined by the characteristics of the signal at the output of the pre-Amplifier and by the TDC binning

Strong interplay between sensor and electronics



UFSD: Low Gain Avalanche Diodes



Adding a highly doped, thin layer of p-implant near the p-n junction creates a high electric field that accelerates the electrons enough to start multiplication (same principle of APD but with much lower gain)

- ▷ Gain changes very smoothly with bias voltage
- Easy to set the optimal value of gain

Aim at something like a pixel detector, but with a much larger signal



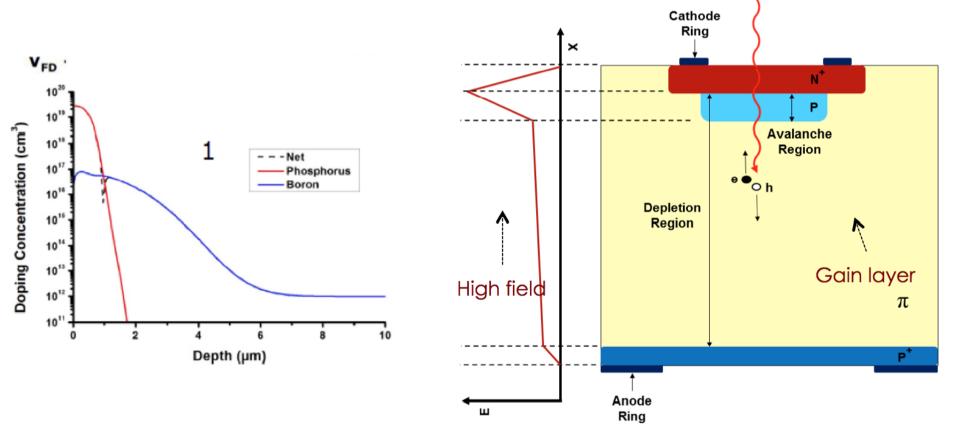
UFSD: Low Gain Avalanche Diodes

The LGAD sensors, as proposed and manufactured by CNM

(National Center for Micro-electronics, Barcelona):

High field obtained by adding an extra doping layer

E ~ 300 kV/cm, closed to breakdown voltage



Ingredients to achieve the very fast timing and high timing resolution:

- Keep the gain around 10-20
- Use thin detectors (50 µm) to:
 - Minimize event-by-event variation of the charge produced by ionization
 - Minimize the rise time of the signal
- Use parallel plate geometry (strip implant ~ strip pitch ≫ thickness) to keep drift velocity as uniform as possible
- Reduce at minimum the shot noise → low gain, cool the detector, use small pads to limit the leakage current

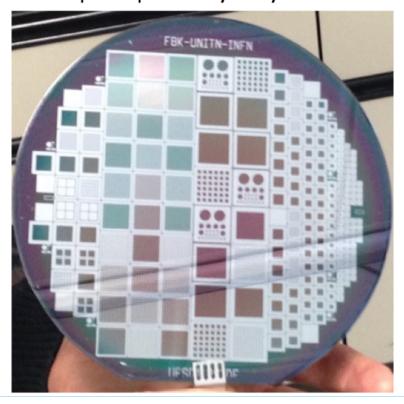
UFSD - Sensors

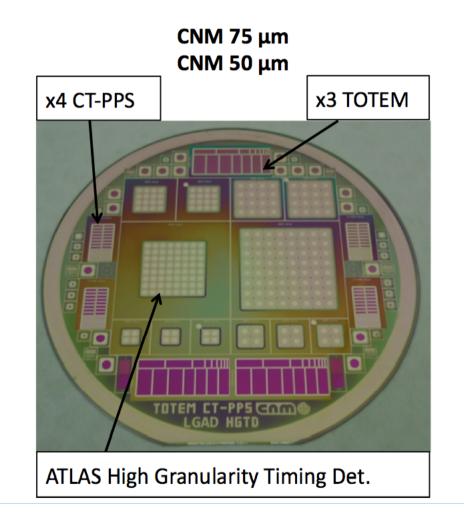
SENSORS - FBK & CNM

FBK 300 µm

Very successful: good gain and overall behaviour (see G. Paternoster talk)

 \rightarrow FBK 50 μ m expected by early 2017

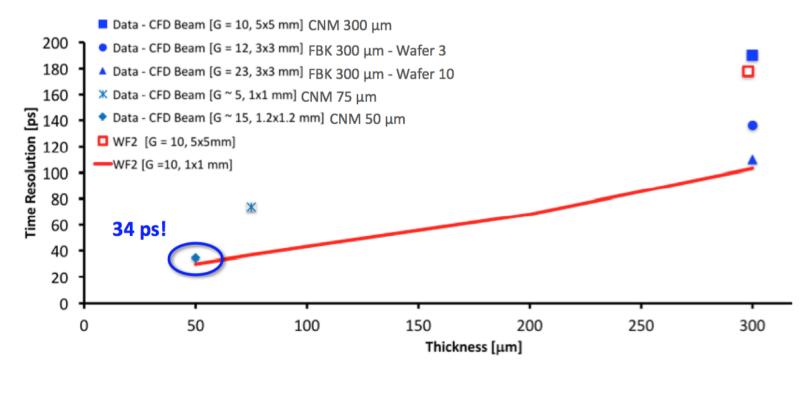






SUMMARY OF UFSD BEAM TEST RESULTS

2014 Frascati: UFSD 7x7mm² 300 μ m (C = 12pF, Gain =10) 2014 CERN: UFSD 7x7mm² 300 μ m (C = 12pF, Gain =10) 2015 CERN: UFSD 3x3mm² 300 μ m (C = 4pF, Gain =10 - 20) 2015 CERN: UFSD 1x1mm² 75 μ m (C = 2pF, Gain =5) 2016 CERN: UFSD 1.2x1.2mm² 50 μ m (C = 3pF, Gain =15)



UFSD - applications

- Particle identification in Time-Of-Flight (TOF) detectors
- Fast triggering
- Forward physics



Thank you for your motivation, your attention, your questions, your interest!!!



